

# Development of Terrestrial Dynamical Cores for E3SM

Gautam Bisht<sup>1</sup>, Jed Brown<sup>2</sup>, Nathan Collier<sup>3</sup>, Jennifer Fredrick<sup>4</sup>,  
Glenn Hammond<sup>4</sup>, Satish Karra<sup>5</sup>, and Mathew Knepley<sup>6</sup>

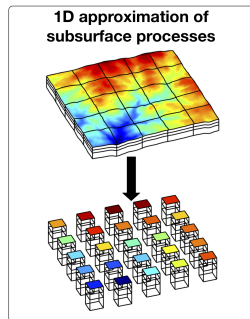
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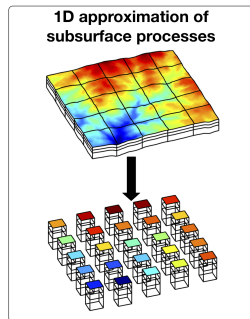
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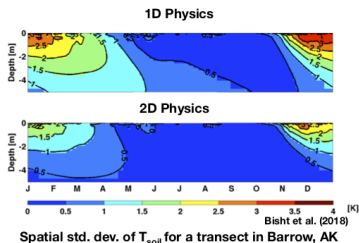
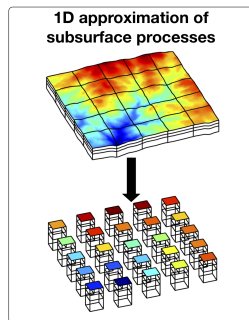
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- ▶ Exclusion of lateral redistribution of subsurface heat leads to an **overestimation** of spatial variability in soil temperature (Bisht et al., 2018)



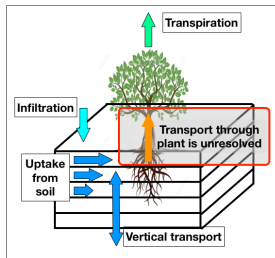
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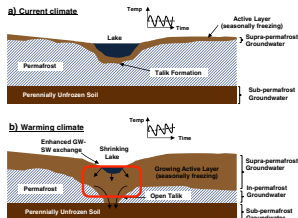
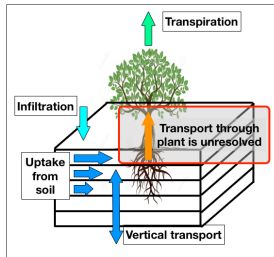
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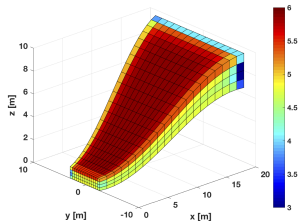
- ▶ Transport of water through soil-plant continuum
- ▶ Advective transport of energy



# Computational challenges for a 3D global LSM

E3SM's 10-year vision of a **sub-kilometer resolution** in terrestrial components imposes several key computation requirements for the terrestrial dynamical core (dycore):

- ▶ Scalable solver for nonlinear parabolic PDE with  $10^{10}$  unknowns
- ▶ Spatial discretization that accounts for **non-orthogonal unstructured grids**
- ▶ **Flexible framework** to assemble a tightly coupled multi-component, multi-physics problem
- ▶ **Runtime configurability** to use a range of numerical algorithms





# Goal

Develop a rigorously verified, spatially adaptive, scalable, multi-physics dycore for **global-scale** modeling of **three-dimensional subsurface** processes in E3SM.

# The coupled thermal-hydrology model

The terrestrial dycore will solve 3D transport of water and energy in the subsurface given by:

$$\frac{\partial}{\partial t}(\rho\phi s) = -\nabla \cdot (\rho\mathbf{q}) + Q_w \quad (1)$$

$$\frac{\partial}{\partial t}(\rho\phi sU + (1 - \phi)\rho_p C_p T) = -\nabla \cdot (\rho\mathbf{q}H - \kappa\nabla T) + Q_e \quad (2)$$

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1. Using **spatial discretization methods** that accounts for non-orthogonal grids
2. Using a flexible framework that supports experimenting with different **temporal discretization** schemes

# Terrestrial Dynamical core (TDycore) library

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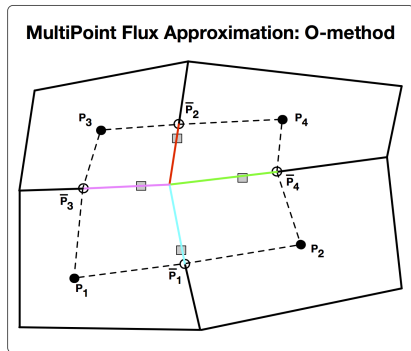
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# Multi Point Flux Approximation: O-Method

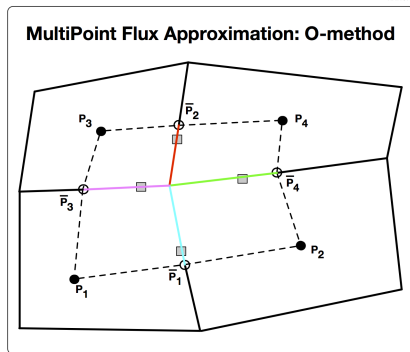
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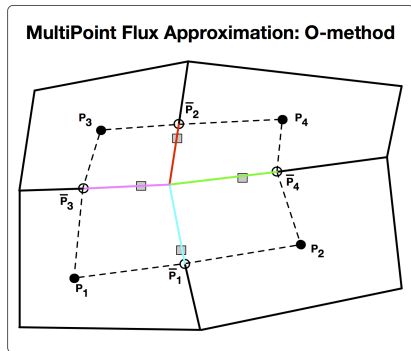


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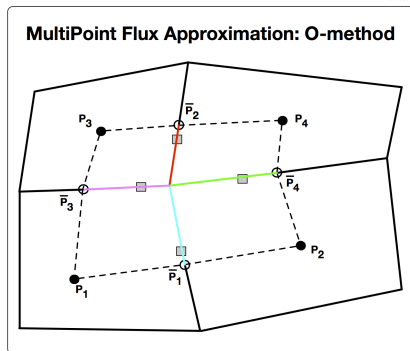
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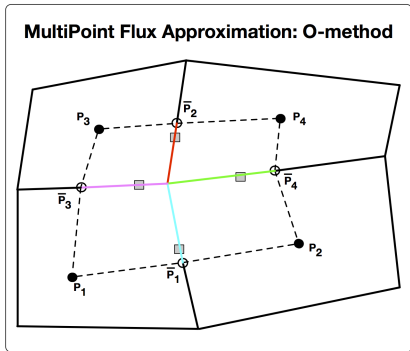
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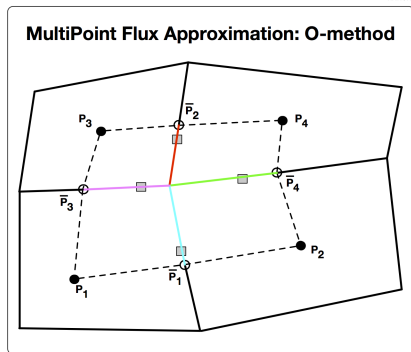
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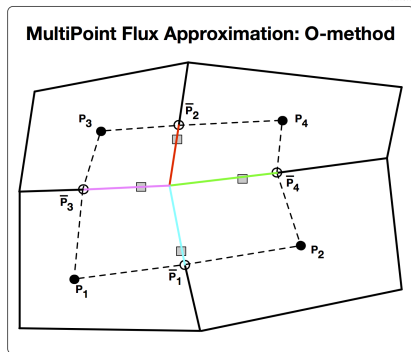
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- ▶ A serial implementation of the method for 2D and 3D grids has been completed



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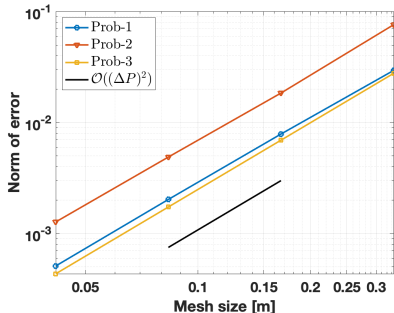
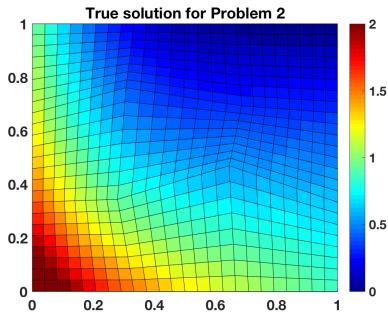
# MPFA-O: Results

Method of Manufactured Solutions (MMS) is used to verify the implementation for a range of problems

1.  $P = 3.14 + x(1 - x) + y(1 - y)$  and  $K = \begin{bmatrix} 5 & 1 \\ 1 & 2 \end{bmatrix}$

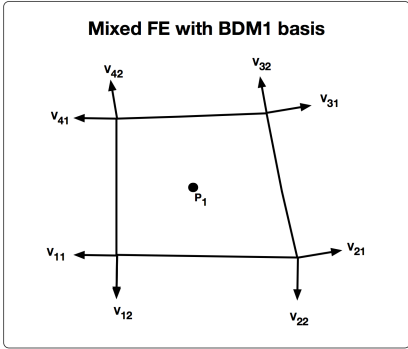
2.  $P = (x - 1)^4 + (1 - x)(1 - y)^3 + \sin(1 - y) \cos(1 - x)$  and  $K = \begin{bmatrix} 5 & 1 \\ 1 & 2 \end{bmatrix}$

3.  $P = x(1 - x) + y(1 - y) + z(1 - z)$  and  $K = \begin{bmatrix} 5 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 3 \end{bmatrix}$



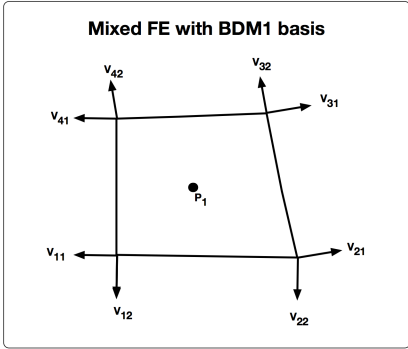
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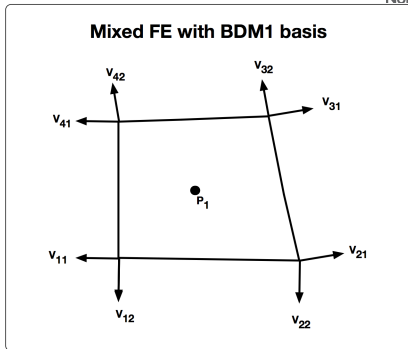
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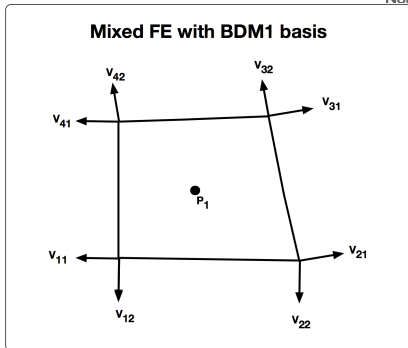
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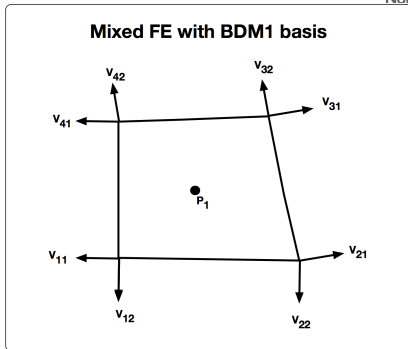
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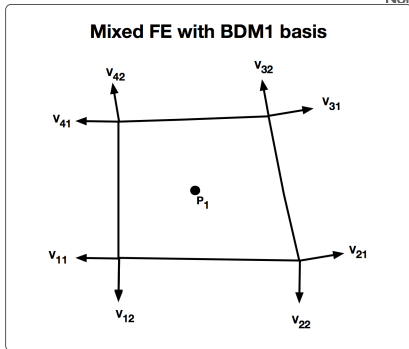
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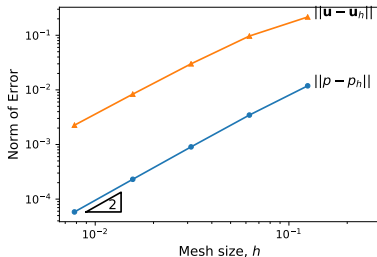
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- ▶ Implementation works on distorted grids in 2D/3D in parallel



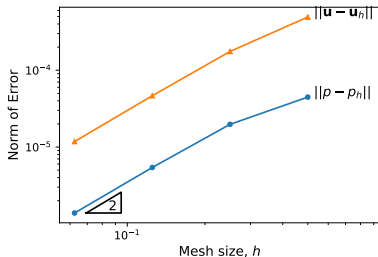
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- ▶ We verify the BDM and WY implementation with the same problems as MPFA-O
- ▶ Obtain 2<sup>nd</sup> order convergence in pressure and velocity on distorted grids in 2D and 3D

### Problem 2



### Problem 3



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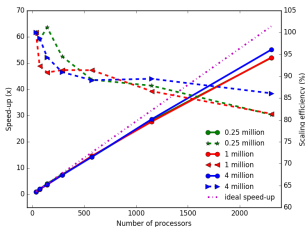
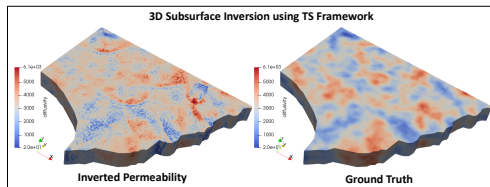
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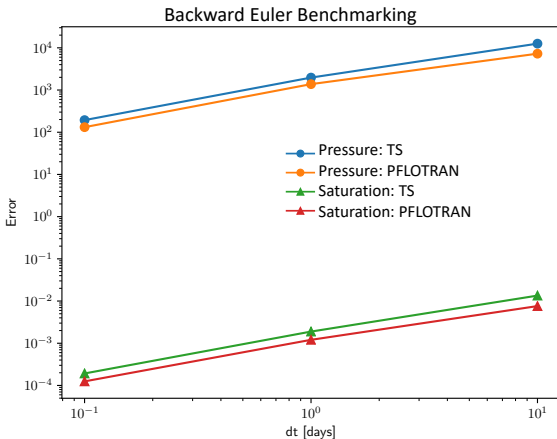


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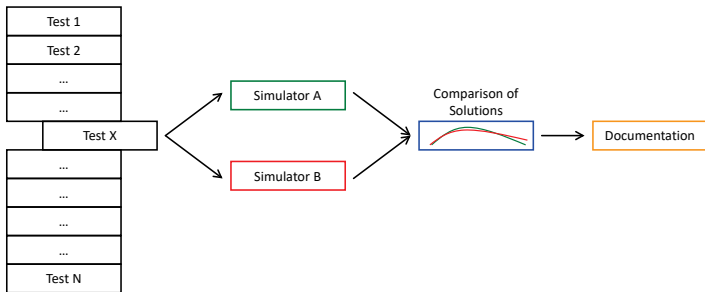


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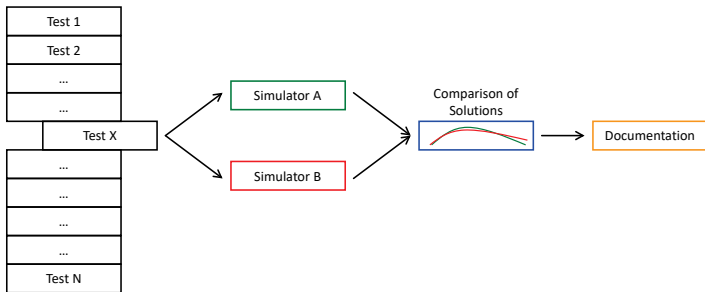
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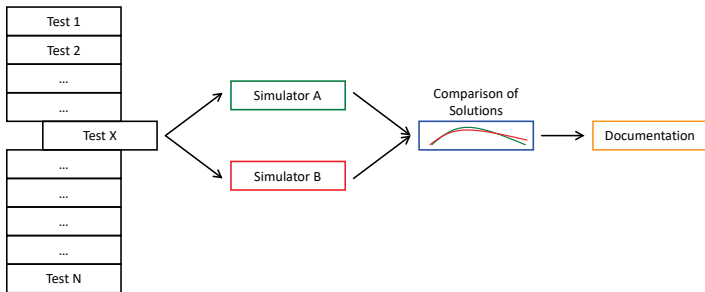
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- ▶ Results are compared among simulators, analytical solutions or empirical datasets
- ▶ Documentation is generated in reStructuredText format and compiled to pdf or html using Sphinx

# Benefits of the V&V Framework

- ▶ Confidence: Quality assurance
- ▶ Automation: Push-button testing in Cloud
- ▶ Maintainability: Python OO design maximizes code reuse and eases future refactoring.
- ▶ Longevity: Adoption by other simulation frameworks will better ensure vitality.
  - ▶ PFLOTRAN will leverage the same framework.



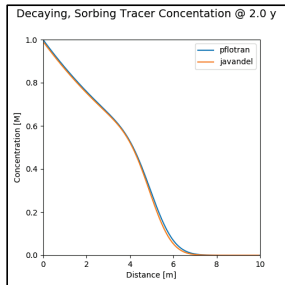
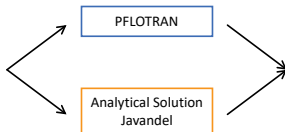
# Example V&V Simulation

## 1D Solute Transport with Linear Sorption and First-Order Decay

- ▶ A recursive search finds a configuration file (.cfg) that specifies that the decay\_and\_sorption test be run by PFLOTRAN and the Javandel analytical solution.
- ▶ An options file (.opt) sets runtime and output options.
- ▶ Results are post-processed and plotted with Matplotlib.

1D Solute Transport, Linear Sorption, First-Order Decay

$$R \frac{\partial C}{\partial t} + v \frac{\partial C}{\partial x} - D \frac{\partial^2 C}{\partial x^2} = -kCR$$



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- ▶ Use the V&V framework to benchmark the dycore against other models (e.g. PFLOTRAN)

## Next steps

- ▶ Extend the serial implementation of MPFA-O method to support multiple processors
- ▶ Perform an inter-comparison of spatial discretization methods
- ▶ Combine the developments in spatial and temporal discretization methods to solve a non-linear, transient subsurface flow problem on non-orthogonal grids
- ▶ Use the V&V framework to benchmark the dycore against other models (e.g. PFLOTRAN)
- ▶ Couple the dycore with E3SM Land Model for a watershed scale simulation

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