

Development of Terrestrial Dynamical Cores for E3SM

Gautam Bisht¹

¹Climate & Ecosystem Sciences Division
Lawrence Berkeley National Laboratory

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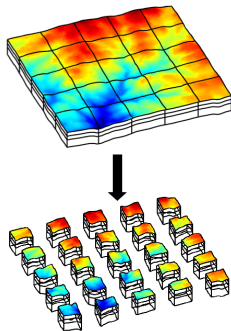
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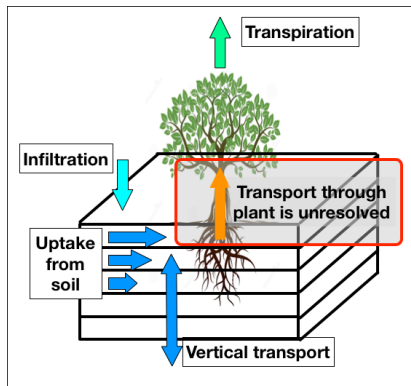
- ▶ Lateral redistribution of water, energy, and nutrients



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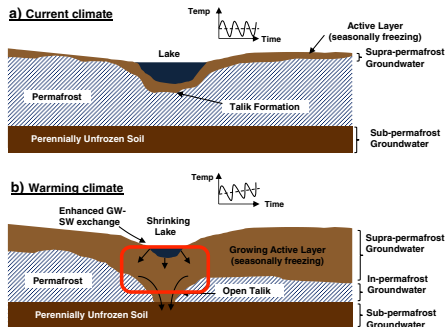
- ▶ Lateral redistribution of water, energy, and nutrients
- ▶ Transport of water through soil-plant continuum



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- ▶ Lateral redistribution of water, energy, and nutrients
- ▶ Transport of water through soil-plant continuum
- ▶ Advective transport of energy



Kurylyk et al. (2014), Earth-Science Reviews

Computational requirements

E3SM's 10-year vision of a sub-kilometer resolution in terrestrial components imposes several key computation requirements for the terrestrial dynamical core (dycore):

- ▶ Scalable solver for nonlinear parabolic PDE with 10^{10} unknowns
- ▶ Support unstructured grids
- ▶ Spatial discretization that accounts for non-orthogonal grids
- ▶ Flexible framework to assemble a tightly coupled multi-component, multi-physics problem
- ▶ Runtime configurability to use a range of numerical algorithms

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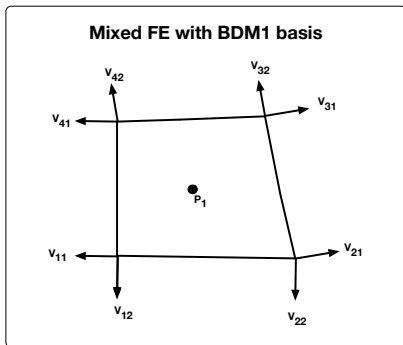
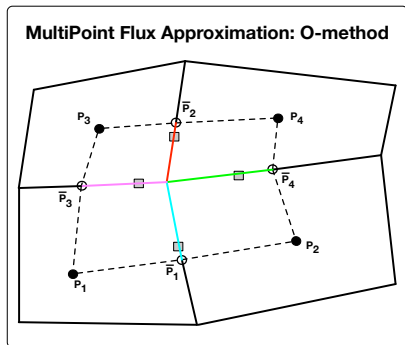
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Develop a rigorously verified, spatially adaptive, scalable, multi-physics dycore for global-scale modeling of three-dimensional subsurface processes in E3SM. The dycore will use PETSc to provide numerical solution of discretized equations.

Early results: Spatial discretization

- ▶ Identified two spatial discretization methods that account for non-orthogonal grids and have been previously applied to solve for flow and transport processes

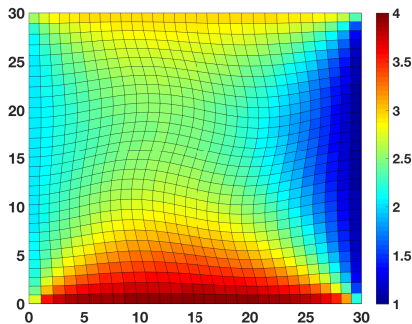


- ▶ Both methods lead to similar set of nonlinear equations with unknowns pressure values at cell centers

Early results: Spatial discretization

- ▶ Developed a prototype code for solving 2D steady-state diffusion equation using MPFA-O method

$$\nabla \cdot (K \nabla P) = 0 \text{ with}$$
$$K = 1, P_{\text{south}} = 4, P_{\text{north}} = 3, P_{\text{right}} = 1, \text{ and } P_{\text{left}} = 2$$

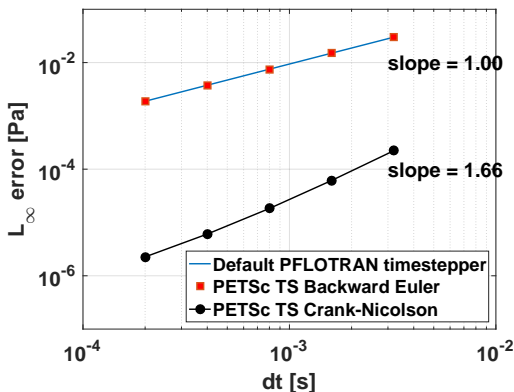


- ▶ Preliminary comparison of our results show good agreement with the MATLAB Reservoir Simulation Toolbox

Early results: Temporal discretization

- ▶ Implemented PETSc TS-based solver in PFLOTRAN, which uses first-order spatial discretization

Problem setup: Evolution of liquid pressure towards a hydrostatic equilibrium starting with homogenous conditions in a 1D soil column

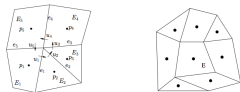


BER-ASCR Partnership

Theory

2092

MARY F. WHEELER AND IVAN YOTOV



A. Five elements sharing a vertex.

B. Pressure stencil.

FIG. 2.3. Intersections of the degrees of freedom in MFME.

2.7. Reduction to a cell-centered stencil. We next describe how the MFME method reduces to a system for the pressures at the cell centers. Let us consider any interior vertex r and suppose that it is shared by k elements E_1, \dots, E_k ; see Figure 2.3(A) for a specific example with 5 elements. We denote the edges (faces) that share the vertex by e_1, \dots, e_k , the velocity basis functions on those edges (faces) that are associated with the vertex by v_1, \dots, v_k , and the corresponding values of the normal components of u_h by w_1, \dots, w_k . Note that for clarity the normal velocities on Figure 2.3(A) are drawn at a distance from the vertex.

Since the quadrature rule $(K^{-1}, \omega)_Q$ localizes the basis functions interaction (see (2.34)–(2.35)), taking $v = v_i$ in (2.41), for example, will only lead to coupling u_h with w_i and w_j . Similarly, w_j will only be coupled with u_h and u_k , etc. Therefore, the k equations obtained from taking $v = v_1, \dots, v_k$ form a linear system for u_1, \dots, u_k , and positive definite.

PROPOSITION 2.7. The $k \times k$ local linear system described above is symmetric and positive definite.
Proof. The system is obtained by taking $v = v_1, \dots, v_k$ in (2.41). On the left-hand side we have

$$(K^{-1}u_h, v_i)_Q = \sum_{j=1}^k u_j (K^{-1}v_j, v_i)_Q = \sum_{j=1}^k a_{ij} u_j, \quad i = 1, \dots, k.$$

Implementation

```
/*
  There will need to be a quadrature for each element type in the
  mesh. Neither is this dim independent. It could be generalized to
  simply use as locations the vertices of the reference element.
*/
#undef __FUNCT__
#define __FUNCT__ "PetscDTWheelerYotovQuadrature"
PetscErrorCode PetscDTWheelerYotovQuadrature(DM dm, AppCtx *user)
{
  PetscFunctionBegin;
  PetscErrorCode ierr;
  ierr = PetscQuadratureCreate(PETSC_COMM_SELF, &(user->q)); CHKERRQ(ierr);
  PetscInt dim=2, nq=4;
  PetscReal *x, *w;
  ierr = PetscMalloc1(nq*dim, &x); CHKERRQ(ierr);
  ierr = PetscMalloc1(nq, &w); CHKERRQ(ierr);
  x[0] = -1.0; x[1] = -1.0;
  x[2] = 1.0; x[3] = -1.0;
  x[4] = -1.0; x[5] = 1.0;
  x[6] = 1.0; x[7] = 1.0;
  w[0] = 0.25; w[1] = 0.25; w[2] = 0.25; w[3] = 0.25;
  ierr = PetscQuadratureSetData(user->q, dim, 1, nq, x, w); CHKERRQ(ierr);
  PetscFunctionReturn(0);
}
```

- ▶ Discussions between BER and ASCR colleagues have been extremely useful in translating the mixed FE theory into code
- ▶ Application of PETSc's Discretization Technology (DT) capability to mFE discretization is expected to improve DT

Thank you