

Computational techniques for accelerating quantum molecular dynamics simulation of the solid electrolyte interface (SEI) in Li-ion batteries

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Molecular Dynamics



 $Si_{0.12}Al_{0.88}$ alloy with 200 atoms

Parameters taken from [Ko-Chan-Kim-Chelikowsky, 2011]

- Temperature: 973K
- Nose-Hoover thermostat 51 basis per atom, 4x4x4
- element partition
- $\Delta t = 2.4 fs$
- $E_{cut} = 10 \ au$
- Also compare with SIESTA.





Total pair correlation function

The number of atoms in the (1,1,1) element along the MD trajectory.

OpenMP/MPI Parallelization

The inter-element parallelization has been done using MPI, with a rather general data structure for data communication and converting matrices to different formats (DG native, ScaLAPACK, PEXSI, Fourier, etc.)

Intra-element parallelization: Reduce the computational time for generating the adaptive local basis functions in the local element, and the time for constructing the DG Hamiltonian matrix.

OpenMP level (already used for MD simulation, etc.) Compatible with next generation architecture



Total SCF time reduced from 180.2 sec (OMP=1) to 29.4 sec (OMP=12)

MPI level: Initial work for PWDFT: Can use more than 160 cores with 70 fold speedup for generating the basis.





inhomogeneous systems. $\eta_{i,R_{K}}^{2} = \gamma_{1}(J_{K}) \left\| \left(-\frac{1}{2}\Delta + V_{\text{eff}} - \varepsilon_{i,\mathcal{J}} \right) u_{i,\mathcal{J}} \right\|_{L}^{2} \qquad \eta_{i,K}^{2} = \eta_{i,R_{K}}^{2} + \eta_{i,G_{K}}^{2} + \eta_{i,V_{K}}^{2}$ $\eta_{i,G_K}^2 = \frac{1}{4} \sum_{F \in \mathcal{O}_K} \gamma_2(J_F) \left\| \left[\left[\nabla u_{i,\mathcal{J}} \right] \right] \right\|_F^2$ $\eta_i^2 = \sum_{K \in \mathcal{T}} \eta_{i,K}^2$ $\eta_{i,V_K}^2 = \frac{1}{4} \sum_{F \subset \partial K} \gamma_2(J_F) \alpha^2(J_F) \left\| \left[\left[u_{i,\mathcal{J}} \right] \right] \right\|_F^2.$

Measure the error in the energy norm



 10^{-6} $1 \qquad 2 \qquad 3 \qquad 4 \qquad 5$ Step of refinement

0 1 2 3 4 5 Step of refinement



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A Posteriori Error Estimator

A posteriori error estimator:

• Measuring the accuracy of eigenvalues and densities without performing an expensive converged calculation, or

benchmarking with another code. Optimal non-uniform allocation of basis functions for

 $\|u\|_{E,\mathcal{T}}^{2} := \sum_{K \in \mathcal{T}} \frac{1}{2} \|\nabla u_{K}\|^{2} + \sum_{F \in \mathcal{C}} \alpha(J_{F}) \|[[u]]\|_{F}^{2}$

Under certain assumptions, we can show the reliability of the estimator (ξ_i , G_i are high order terms)

 $\left\| u_{i,\mathcal{J}} - u_i \right\|_{E,\mathcal{T}} \lesssim \eta_i + \left(1 + \sqrt{\gamma_{1,\mathcal{J}}} \right) \xi_i$

 $\left|\lambda_i - \lambda_{i,\mathcal{J}}\right| \lesssim \eta_i^2 + G_i$

Example: Graphene oxide with 160 atoms



10⁻³ Max Force Error – U. Ref. Max Force Error – N.U. Ref. Mean Force Error – U. Ref. Mean Force Error – N.U. Ref. 2 3 4 5 Step of refinement

→ ABINIT → DGDFT U. Basis. ◆ DGDFT N.U. Basis

improves the accuracy by orders of magnitude without increasing the number of basis functions.

Error per atom of total energy PEXSI

PEXSI: Pole EXpansion and Selected Inversion

Accurate evaluation of the electron density, energy, and atomic force with at most $O(N^2)$ scaling.



PEXSI applied to DG-generated graphene matrices.



2013

2012

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