

FASTMath Iterative Solver Technologies

Nonlinear, linear and eigenvalue iterative solvers are the key computational kernel in many application's simulations code. FASTMath has a robust research program in developing, implementing, and supporting a variety of iterative solvers for massively parallel computing systems.

Reducing Communication in Algebraic Multigrid

Objectives

- Algebraic multigrid (AMG) methods have shown excellent weak scalability on distributedmemory architectures, however the increasing fill-in and communication complexities on coarser levels have led to decreased performance on modern multicore architectures.
- The development of new methods with reduced communication is essential.

Additive AMG Variants

- Classical additive AMG methods have improved communication complexities per cycle, but converge significantly slower than multiplicative AMG. Mult-additive AMG, a new additive variant with reduced communication, in which the interpolation operator is replaced by a smoothed truncated prolongator, converges significantly faster than additive AMG.
- Further reductions in communication can be achieved by omitting most of the smoothing portion in the mult-additive V-cvcle, leading to a simplified mult-additive variant.



Source: LLNL hypre Team

Computing many eigenpairs of sparse matrices

Application driver:

Material science and chemistry, especially excited state calculation

Limitations of the existing solver:

Limited amount of parallelism in a standard Krylov subspace method (e.g. PARPACK)

3 250 3 200

Multiple shift-invert scalability

Rayleigh-Ritz (RR) procedure often the bottleneck

Alternative strategies:



- More parallelism, no big RR calculation, but
- Need to estimate eigenvalue distribution
- Compute interior eigenvalues
- Polynomial filtering (See Chelikowsy poster)
- Shift-invert Lanczos
 - Contour integral method
- lacobi-Davidson
- · Manage/optimize task distribution/load balancing





- Barzilai Borwein line search
- Few RR calculation
- Block computation, more GEMMs Rlj=AXlj+µXlj (Xlj1TXlj-I) X1/+1 =X1/ -aM1-1 R1/, where a=
- trace $(\Delta R J j \uparrow T \Delta X J j) / ||\Delta R J j|| J F \uparrow 2$ Source: LBNL Arpack Team



Parallel AMG Based on Energy Minimization





Broad Accelerator Support via OpenCL

Porting our existing CUDA-based operations to OpenCL allows for leveraging the performance of both current and future hardware from different vendors. By supplementing vendor-provided BLAS implementation by domain-specific kernels, high performance is obtained.



More Information: http://www.fastmath-scidac.org or contact Lori Diachin, LLNL, diachin2@llnl.gov, 925-422-7130





Lawrence Livermore National Laboratory



Performance

Scalability

profile

¢.







Sandia National